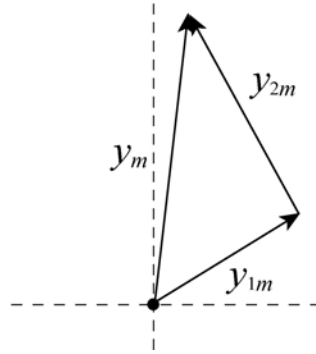


16-35. The phasor diagram is shown below: y_{1m} and y_{2m} represent the original waves and y_m represents the resultant wave.



The phasors corresponding to the two constituent waves make an angle of 90° with each other, so the triangle is a right triangle. The Pythagorean theorem gives

$$y_m^2 = y_{1m}^2 + y_{2m}^2 = (3.0 \text{ cm})^2 + (4.0 \text{ cm})^2 = (5.0 \text{ cm})^2.$$

Thus $y_m = 5.0 \text{ cm}$.

Note: When adding two waves, it is convenient to represent each wave with a phasor, which is a vector whose magnitude is equal to the amplitude of the wave. The same result, however, could also be obtained as follows: Writing the two waves as $y_1 = 3 \sin(kx - \omega t)$ and $y_2 = 4 \sin(kx - \omega t + \pi/2) = 4 \cos(kx - \omega t)$, we have, after a little algebra,

$$\begin{aligned} y &= y_1 + y_2 = 3 \sin(kx - \omega t) + 4 \cos(kx - \omega t) = 5 \left[\frac{3}{5} \sin(kx - \omega t) + \frac{4}{5} \cos(kx - \omega t) \right] \\ &= 5 \sin(kx - \omega t + \phi) \end{aligned}$$

where $\phi = \tan^{-1}(4/3)$. In deducing the phase ϕ , we set $\cos \phi = 3/5$ and $\sin \phi = 4/5$, and use the relation $\cos \phi \sin \theta + \sin \phi \cos \theta = \sin(\theta + \phi)$.

16-37. (a) Using the phasor technique, we think of these as two “vectors” (the first of “length” 4.6 mm and the second of “length” 5.60 mm) separated by an angle of $\phi = 0.8\pi$ radians (or 144°). Standard techniques for adding vectors then lead to a resultant vector of length 3.29 mm.

(b) The angle (relative to the first vector) is equal to 88.8° (or 1.55 rad).

(c) Clearly, it should be “in phase” with the result we just calculated, so its phase angle relative to the first phasor should be also 88.8° (or 1.55 rad).

30-28. (a) We use $I = \varepsilon/X_c = \omega_d C \varepsilon$.

$$I = \omega_d C \varepsilon_m = 2\pi f_d C \varepsilon_m = 2\pi(1.00 \times 10^3 \text{ Hz})(1.50 \times 10^{-6} \text{ F})(30.0 \text{ V}) = 0.283 \text{ A} .$$

(b) $I = 2\pi(8.00 \times 10^3 \text{ Hz})(1.50 \times 10^{-6} \text{ F})(30.0 \text{ V}) = 2.26 \text{ A}$.

29. (a) The current amplitude I is given by $I = V_L/X_L$, where $X_L = \omega_d L = 2\pi f_d L$. Since the circuit contains only the inductor and a sinusoidal generator, $V_L = \varepsilon_m$. Therefore,

$$I = \frac{V_L}{X_L} = \frac{\varepsilon_m}{2\pi f_d L} = \frac{30.0 \text{ V}}{2\pi(1.00 \times 10^3 \text{ Hz})(50.0 \times 10^{-3} \text{ H})} = 0.0955 \text{ A} = 95.5 \text{ mA}.$$

(b) The frequency is now eight times larger than in part (a), so the inductive reactance X_L is eight times larger and the current is one-eighth as much. The current is now

$$I = (0.0955 \text{ A})/8 = 0.0119 \text{ A} = 11.9 \text{ mA}.$$

30. (a) The current through the resistor is

$$I = \frac{\varepsilon_m}{R} = \frac{30.0 \text{ V}}{50.0 \Omega} = 0.600 \text{ A} .$$

(b) Regardless of the frequency of the generator, the current is the same, $I = 0.600 \text{ A}$.

33. (a) The generator emf and the current are given by

$$\varepsilon = \varepsilon_m \sin(\omega_d t - \pi/4), \quad i(t) = I \sin(\omega_d t - 3\pi/4).$$

The expressions show that the emf is maximum when $\sin(\omega_d t - \pi/4) = 1$ or

$$\omega_d t - \pi/4 = (\pi/2) \pm 2n\pi \quad [n = \text{integer}].$$

The first time this occurs after $t = 0$ is when $\omega_d t - \pi/4 = \pi/2$ (that is, $n = 0$). Therefore,

$$t = \frac{3\pi}{4\omega_d} = \frac{3\pi}{4(350 \text{ rad/s})} = 6.73 \times 10^{-3} \text{ s} .$$

(b) The current is maximum when $\sin(\omega_d t - 3\pi/4) = 1$, or

$$\omega_d t - 3\pi/4 = (\pi/2) \pm 2n\pi \quad [n = \text{integer}].$$

The first time this occurs after $t = 0$ is when $\omega_d t - 3\pi/4 = \pi/2$ (as in part (a), $n = 0$). Therefore,

$$t = \frac{5\pi}{4\omega_d} = \frac{5\pi}{4(350 \text{ rad/s})} = 1.12 \times 10^{-2} \text{ s} .$$

(c) The current lags the emf by $+\pi/2$ rad, so the circuit element must be an inductor.

(d) The current amplitude I is related to the voltage amplitude V_L by $V_L = IX_L$, where X_L is the inductive reactance, given by $X_L = \omega_d L$. Furthermore, since there is only one element in the circuit, the amplitude of the potential difference across the element must be the same as the amplitude of the generator emf: $V_L = \varepsilon_m$. Thus, $\varepsilon_m = I\omega_d L$ and

$$L = \frac{\varepsilon_m}{I\omega_d} = \frac{30.0\text{V}}{(620 \times 10^{-3} \text{ A})(350 \text{ rad/s})} = 0.138 \text{ H}.$$

Note: The current in the circuit can be rewritten as

$$i(t) = I \sin\left(\omega_d t - \frac{3\pi}{4}\right) = I \sin\left(\omega_d t - \frac{\pi}{4} - \phi\right)$$

where $\phi = +\pi/2$. In a purely inductive circuit, the current lags the voltage by 90° .